

Image Processing and Scene Interpretation - Artificial Intelligence in Operation

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The AI Landscape









Agenda

- **Basic ingredients for Scene Interpretation**
- **Object Recognition with SIFT Features**
- **Ontologies with OWL**
- **Probabilistic Scene Interpretation**

Scene Interpretation (1)



**Scene
interpretation
means
understanding
every-day
occurrences ...**

Scene Interpretation (2)



... or recognizing
rare events

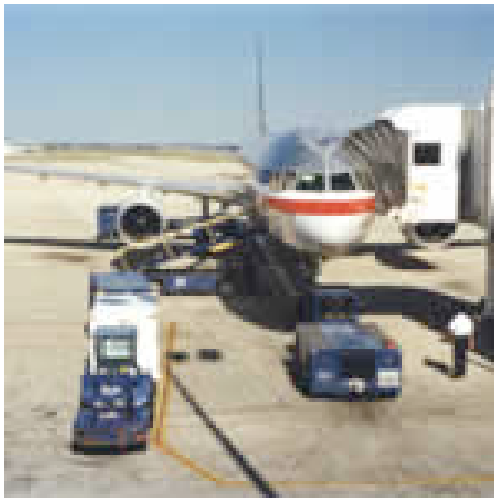


Some Application Scenarios for Scene Interpretation

- **Cameras monitoring parking lots, railway platforms, supermarkets, nuclear power plants, ...**
- **Street traffic observations (long history)**
- **Video archiving and retrieval**
- **Soccer game analysis**
- **Smart room cameras, monitoring of elderly**
- **Autonomous robot applications
(e.g. robot watchmen, playmate for children, assistance for elderly)**
- **Situation assessment**

Significant progress in the last 35 years

Activity Recognition at Blagnac Airport



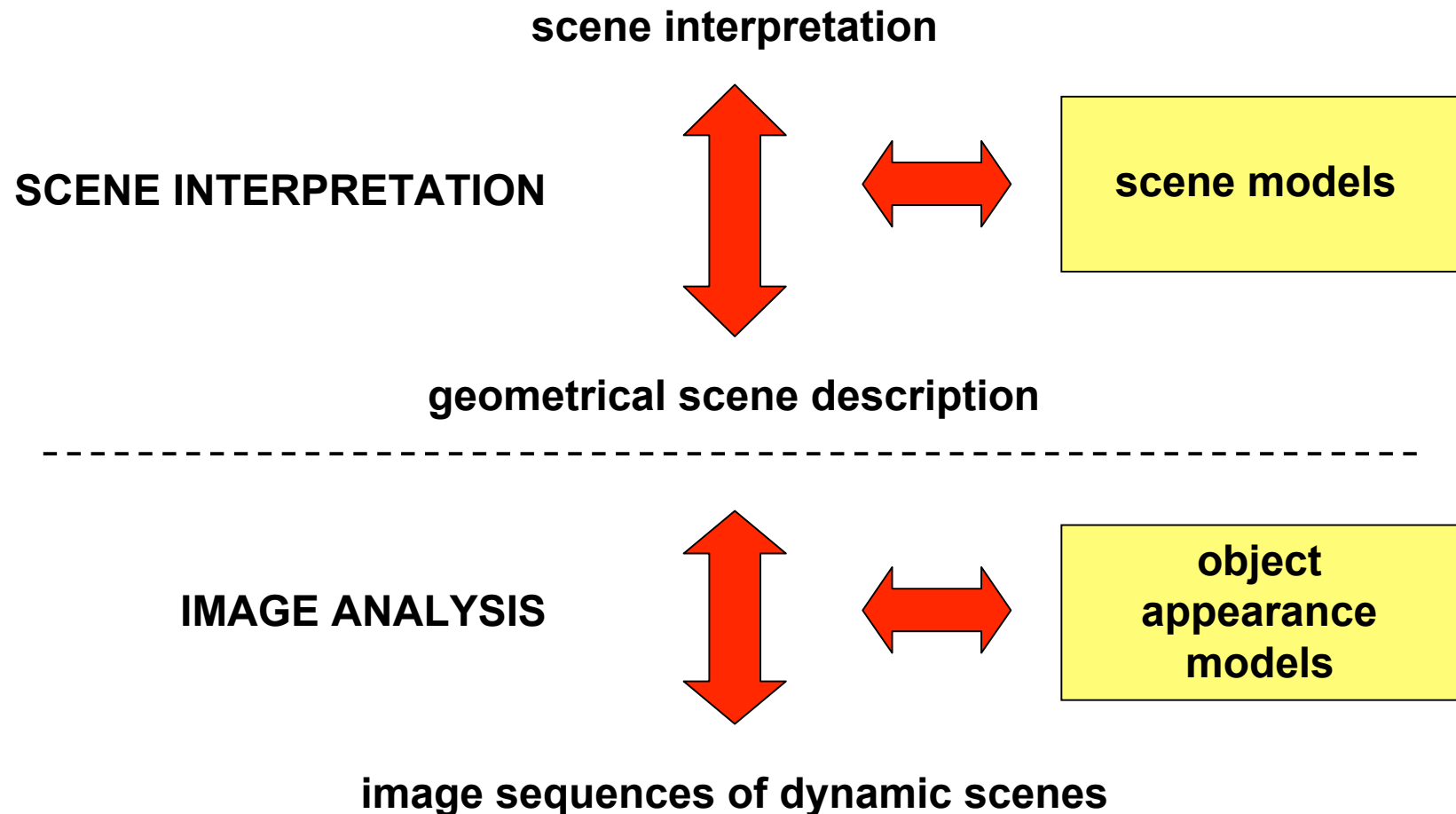
Application scenario

- Aircraft servicing operations at Toulouse-Blagnac Airport are observed by eight cameras
- Moving objects are tracked by a low-level vision system
- Activities such as refueling or baggage unloading are recognised by a high-level vision system

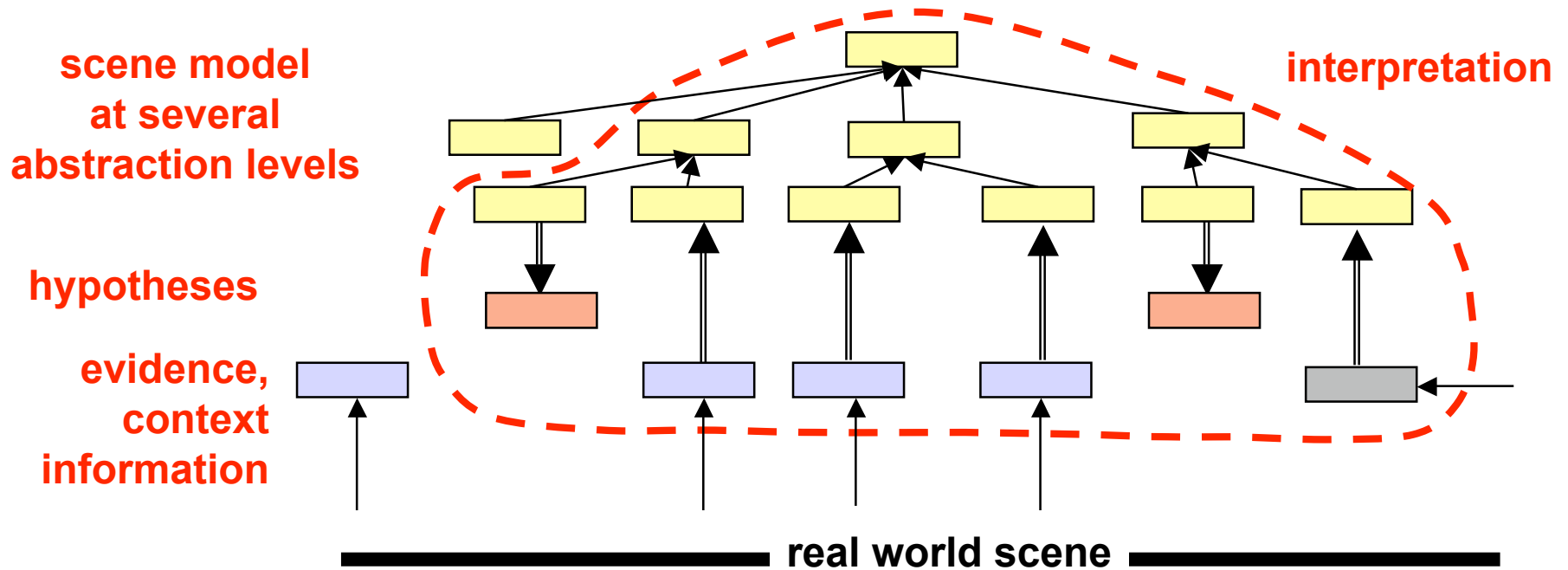
Project goals

- Reliable on-line interpretation of extended multi-camera video sequences
- Learning new activities from examples
- Robust recognition performance based on a rich domain ontology

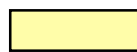
Basic Structure of a Knowledge-based Vision System



Generic Scene Interpretation Process



concepts



context



hypotheses



evidence



Technological Challenges of Scene Interpretation Tasks

- **Problem area combines Computer Vision (CV) and Artificial Intelligence (AI), not well attended by CV and AI research**
- **Reliable object recognition has progressed but is still a bottle-neck**
- **Interpretations may require large knowledge bases and common-sense reasoning**
- **Visual learning and adaptation may be necessary to build up and maintain knowledge bases**
- **Robust interpretation processes must be devised to cope with uncertain and incomplete visual information**
- **Economical application development requires a generic approach**

But: High-level context may support low-level image analysis!

Advances in Image Analysis: SIFT Features

- Create object models in terms of sets of scale and rotation invariant SIFT features
- For recognition, use SIFT features of unknown object as index into model base
- Verify hit by least-squares fit

Detect "interest points" in image at multiple scales

Compute rich local description of image intensities at keypoints

Determine one or more main orientations

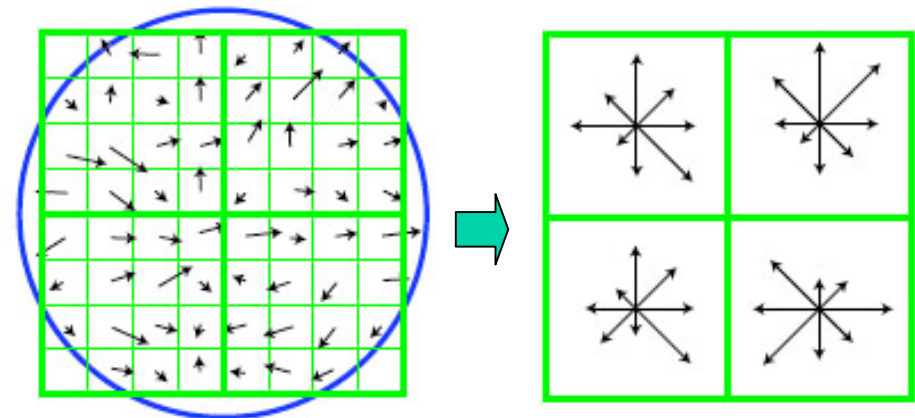


Image gradients

Keypoint descriptors

SIFT-based Object Recognition



training images

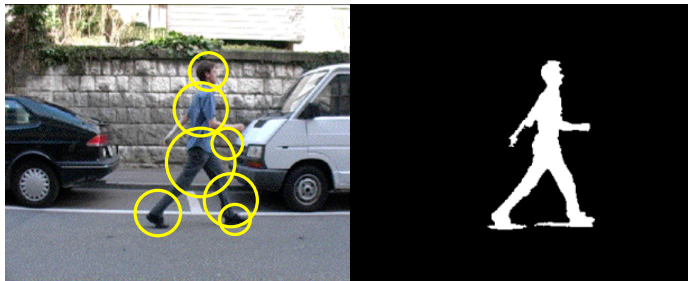


cluttered image

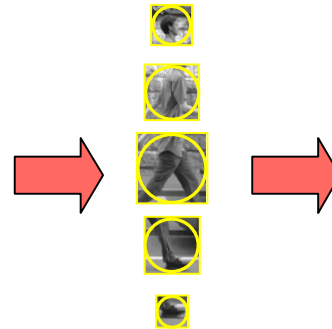


recognized objects

Learning Appearance Models

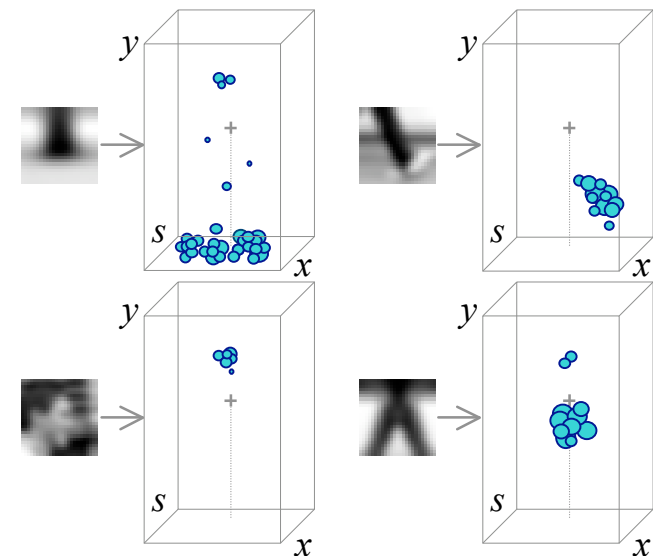


105 training images
(+ motion segmentation)



Appearance codebook

- Learn appearance codebook
 - Extract patches at DoG interest points
 - Agglomerative clustering \Rightarrow codebook
- Learn spatial distributions
 - Match codebook to training images
 - Record matching positions on object



Spatial occurrence distributions

Car Recognition by Appearance Models



- **Recognizes different kinds of cars**
- **Robust to clutter, occlusion, noise, low contrast**

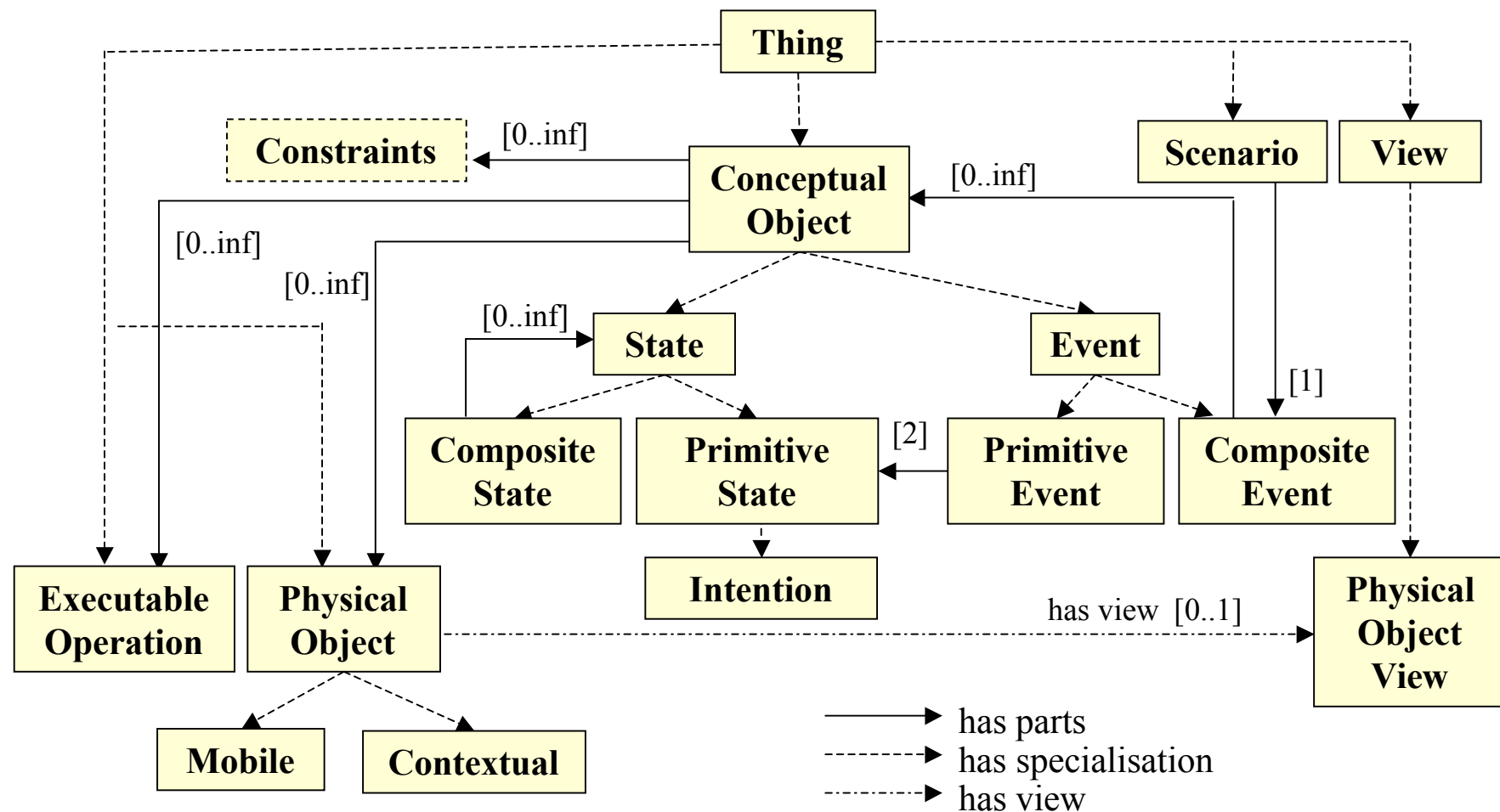
Modelling High-Level Knowledge

- **Model-based scene interpretation requires extensive knowledge bases**
=> formal representation framework and reasoning support needed
- **Standardized knowledge representation with the Semantic Web ontology language OWL and RDF**
 - definition of classes with properties (e.g. "Person", "Vehicle")
 - definition of relationships between classes (e.g. subclassOf, disjointWith)
 - definition of individuals (e.g. "GPU-Access-Area", "Front-Loading-Area")
 - definition of class memberships
 - consistency checking
- **Commercially available reasoning systems (e.g. Pellet, Racer)**

Interplay of OWL knowledge base with scene interpretation is current research topic

Example: Upper Model for Activity Recognition

Definition of ontological relationships between essential concepts



Protégé Ontology Editor for OWL

Definition of "Vehicle-Enters-Zone" for aircraft activity recognition

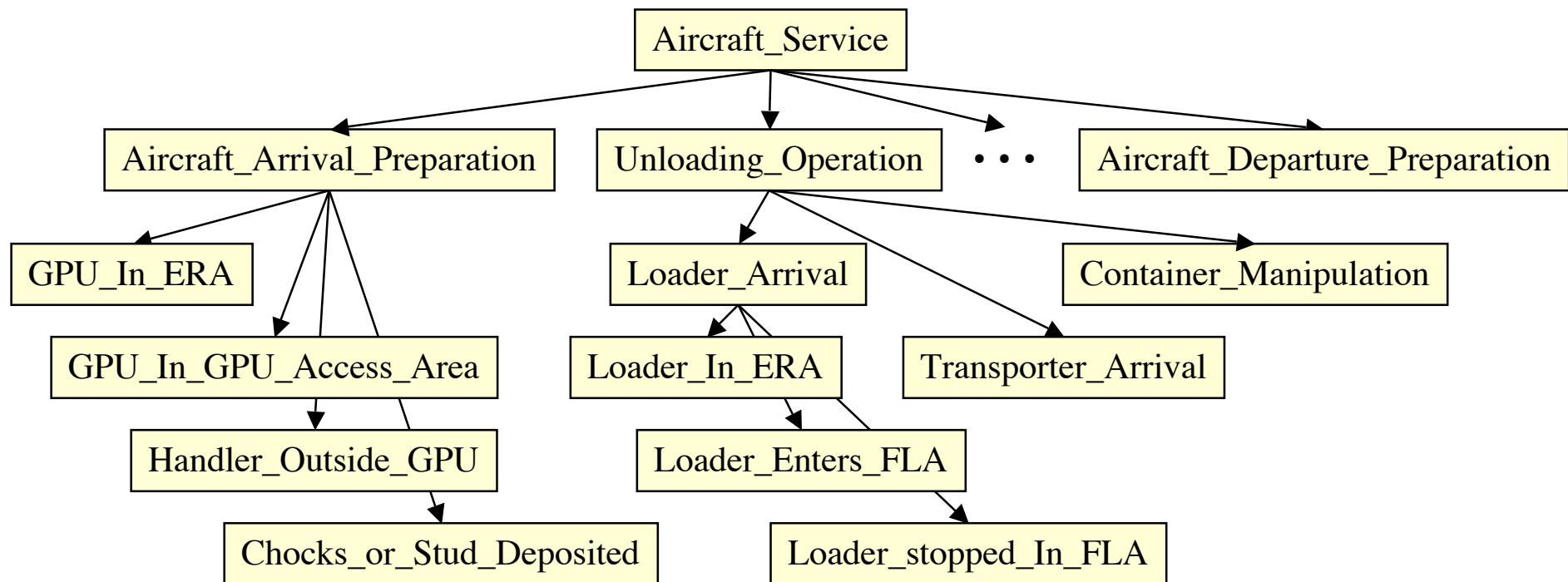
The screenshot displays the Protégé Ontology Editor interface. On the left, a hierarchical tree view shows the ontology structure. The 'Vehicle-Enters-Zone' class is selected and highlighted in yellow. The right pane shows the definition of this class, which is a 'Primitive-Event' with four properties, each with a cardinality of 'exactly 1':

- has-part-time-point-begin exactly 1 Time-Point-Begin
- has-part-time-point-end exactly 1 Time-Point-End
- has-part-vehicle-inside-zone exactly 1 Vehicle-Inside-Zone
- has-part-vehicle-outside-zone exactly 1 Vehicle-Outside-Zone

The 'Vehicle-Enters-Zone' class is highlighted in yellow in the right pane. Above the definition list, there is a toolbar with icons for adding, removing, and deleting elements.

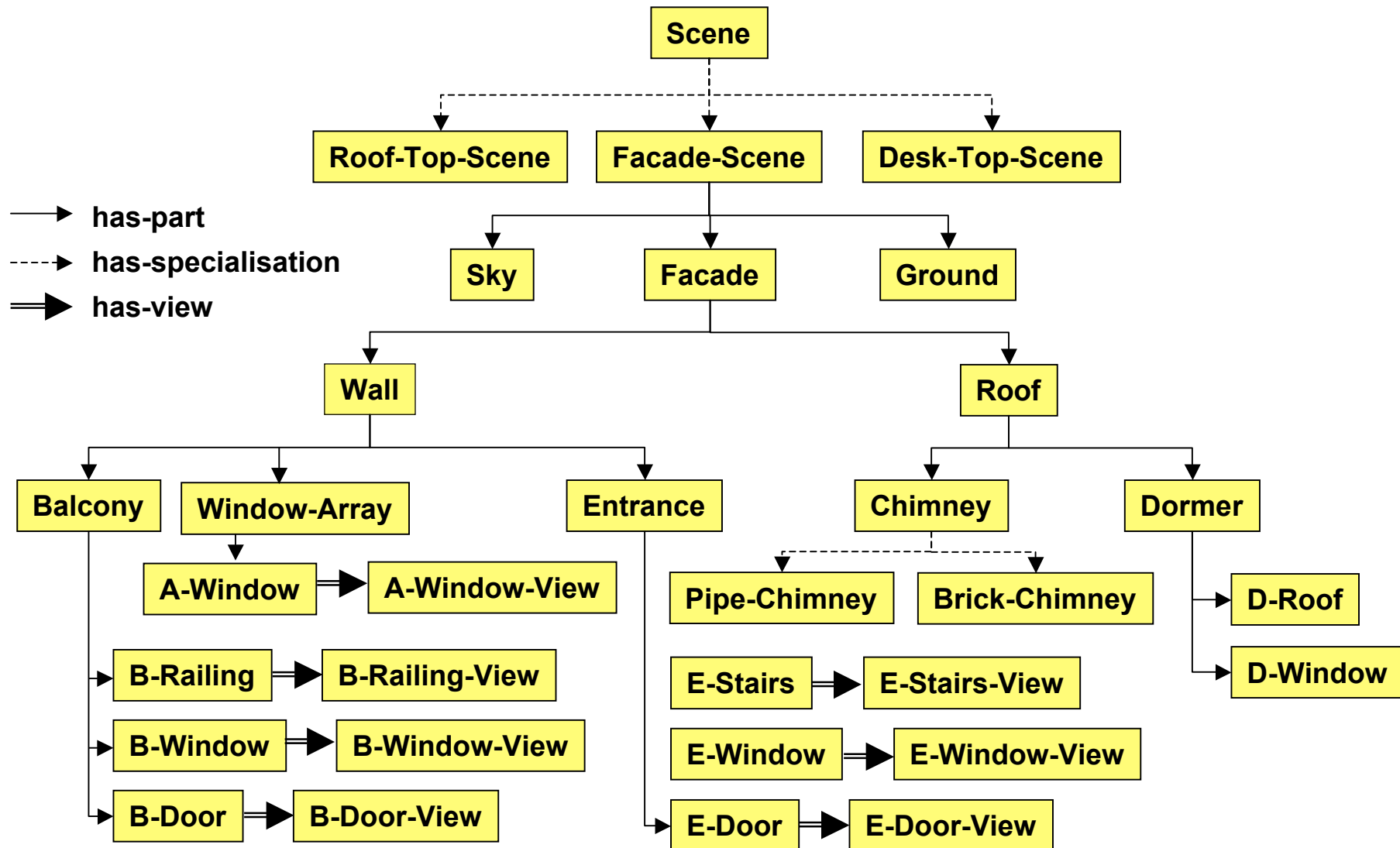
Compositional Hierarchy for Aircraft Services

Compositional (or part-of) hierarchies are the backbone for scene interpretation

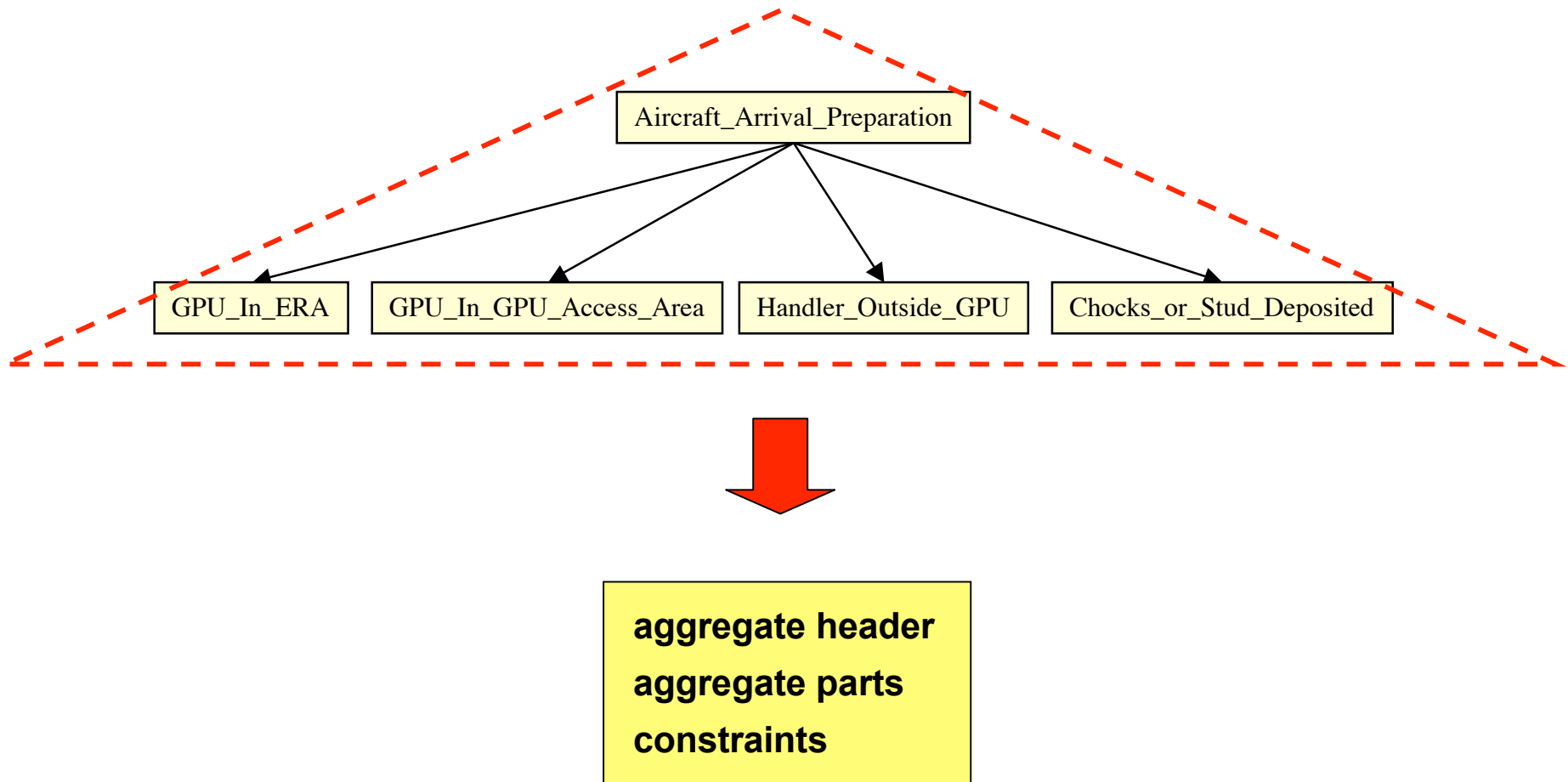


→ = part-of

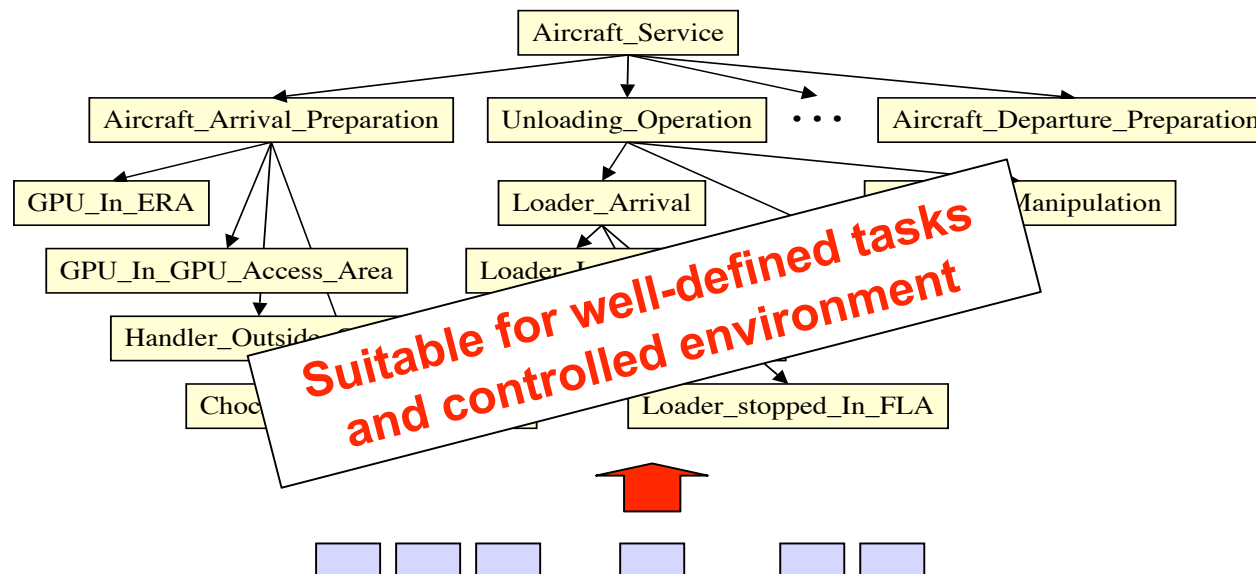
Compositional Hierarchy for Facade Scenes



Generic Object-oriented Aggregate Definitions



Simple Bottom-up Scene Interpretation

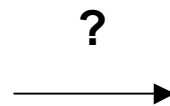
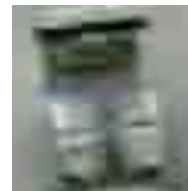


- Bottom-up image analysis provides primitive pieces of evidence
- Evidence instantiates leaves of compositional hierarchy
- Aggregates are instantiated, when all parts are instantiated and constraints are satisfied
- Interpretation is complete, when root of hierarchy is instantiated

Uncertainty Management

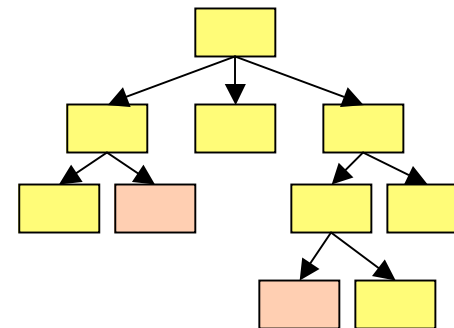
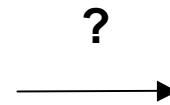
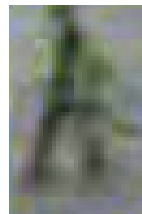
Evidence is often ambiguous or misleading:

- Noise, occlusion, image analysis deficiencies



?
Transporter
GPU
Loader
Service_Vehicle
...

- Multiple roles in scene model



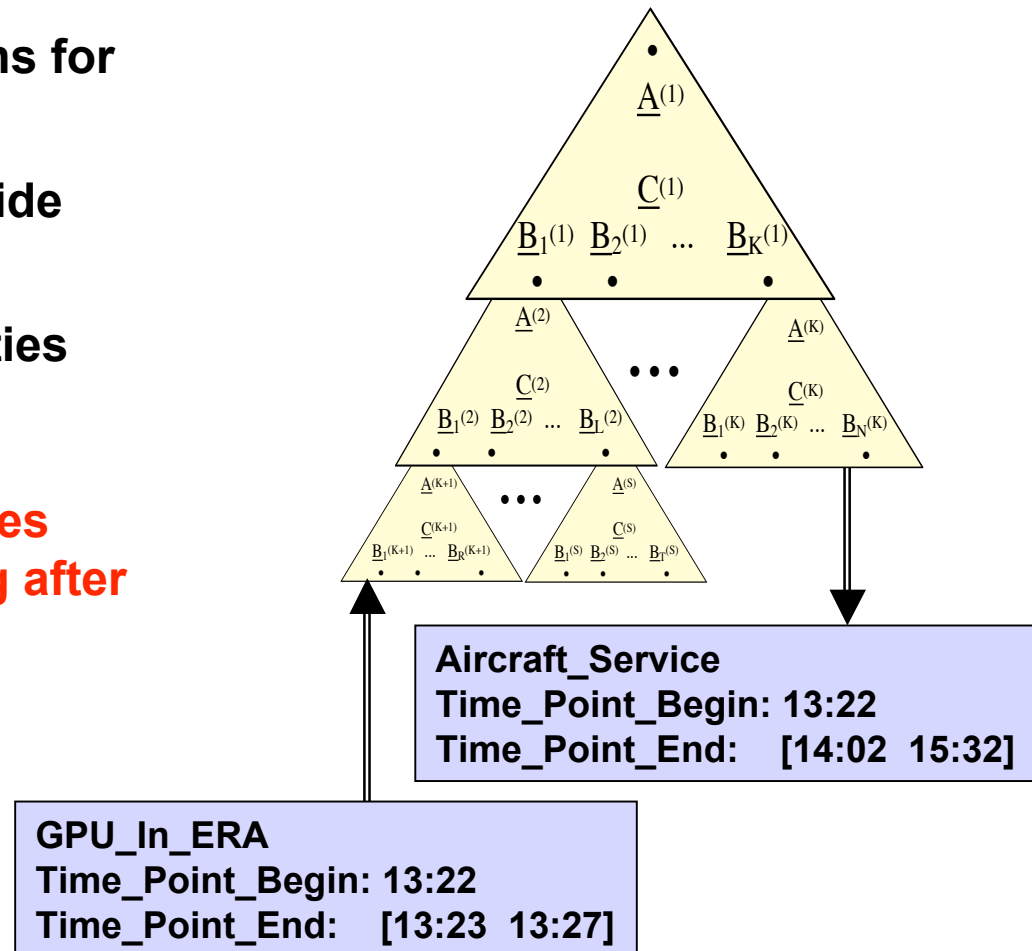
Walking_Person

- False positives and negatives

Probabilistic Guidance

- Provide probability distributions for aggregates in scene model
- Compute dynamic priors to guide evidence assignment
- Obtain estimates for all quantities based on current evidence

Bayesian Compositional Hierarchies
allow efficient probability updating after
evidence assignment steps



Learning

- **Learning methods have greatly improved in the last decade**
 - **SVMs (Support Vector Machines) for pattern classification**
 - **Version Space Learning for logic-based representations**
 - **Probabilistic learning for Bayesian Networks**
- **Learning may be the only way to populate large knowledge bases**
- **Learning visual appearances may require months of continuous presentation of real-life phenomena**
- **Structural learning for high-level knowledge bases is not yet well developed**

Learning of Facade Structures



Summary

- **AI contributes to virtually all technology areas**
- **Computer Vision and AI have to cooperate for scene interpretation**
- **Object Recognition has been improved but remains a bottleneck**
- **The structure of high-level scene models is well understood, but building extensive knowledge bases including common sense knowledge remains a problem**
- **Semantic Web technologies provide a welcome standard for ontology representation and reasoning**

A large, gnarled tree with thick, light-colored branches stands in a field of tall grasses and flowers. The tree's trunk is thick and textured, with several large, curved branches extending outwards. The foliage is green and dense. In the foreground, there is a body of water reflecting the tree and the sky. The sky is blue with some light clouds. The overall scene is a natural, outdoor setting.

Thank you for your attention !