

Probabilistic Inferences in Partonomies

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Uncertainty Management for Scene Interpretation

Interpretations are based on partial and uncertain evidence

⇒ many interpretations possible ("hallucination")

⇒ measure of preference needed

Choice points of the interpretation process:

- assigning evidence to one of many possible scene objects

e.g. tracking result ⇒ transport-object

- assigning a part to one of many aggregates

e.g. transport-saucer ⇒ place-cover

- choosing one of many specializing concepts

e.g. transport-object ⇒ transport-saucer

- ➔ • choosing one of many feature values

e.g. transport-object ⇒ transport-saucer

} part-whole reasoning

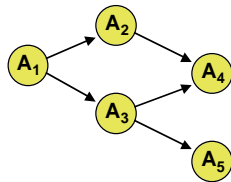
} specialization

Belief Propagation

Bayesian networks (belief nets) are useful for determining the probability of an event from a joint probability distribution given some evidence.

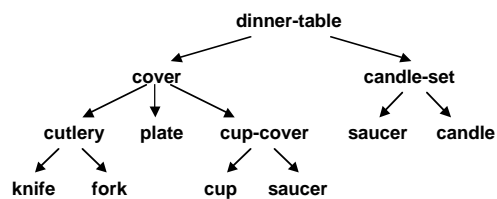
$$\begin{array}{l} \text{JPD} \\ \text{evidence} \end{array} \quad \begin{array}{l} P(A_1, A_2, \dots, A_N) \\ A_i = a, A_j = b, \dots \end{array} \quad \Rightarrow \quad P(A_k = c \mid A_i = a, A_j = b)$$

Solution procedures are known for general and special Bayes Nets (exact and approximate).



How can these techniques be applied to events defined in object-oriented taxonomies and partonomies?

Tree-shaped Bayes Nets for Partonomies?



Binford 92
An aggregate causes parts

Rimey 93:
Tree-shaped part-of nets,
is-a trees, expected-area
nets, and task nets

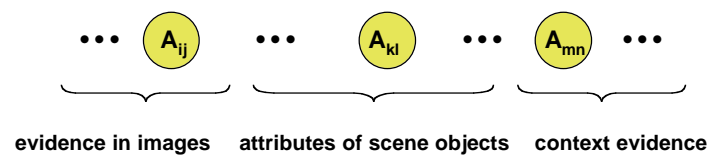
Criticism:

- Aggregate probabilities follow functionally from part probabilities
- Part dependencies are not modelled properly
- Coherent model of objects and object properties required

Table Scenes as Probabilistic Events

Assume that a notion of "object" is given.

A table scene can be viewed as a probabilistic event in terms of the instantiation of a large number of correlated random variables A_{ij} describing attributes of objects (i ranging over objects, j over attributes).



Examples:

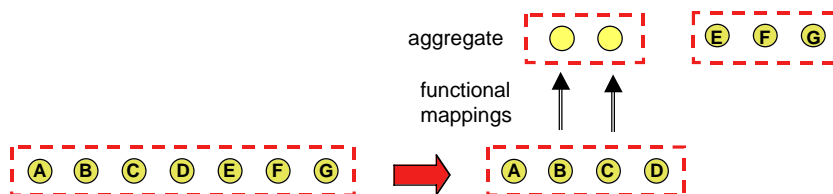
- A_{kl} = location-of-plate
 $\text{domain}(A_{kl}) = \{\text{loc1, loc2, ... , no}\}$
- A_{kl} = color-of-cup
 $\text{domain}(A_{kl}) = \{\text{red, white, ... , no}\}$

Coarsening and Aggregation

A partition is viewed as an artificial structure created to simplify reasoning with an otherwise overly large joint probability distribution.

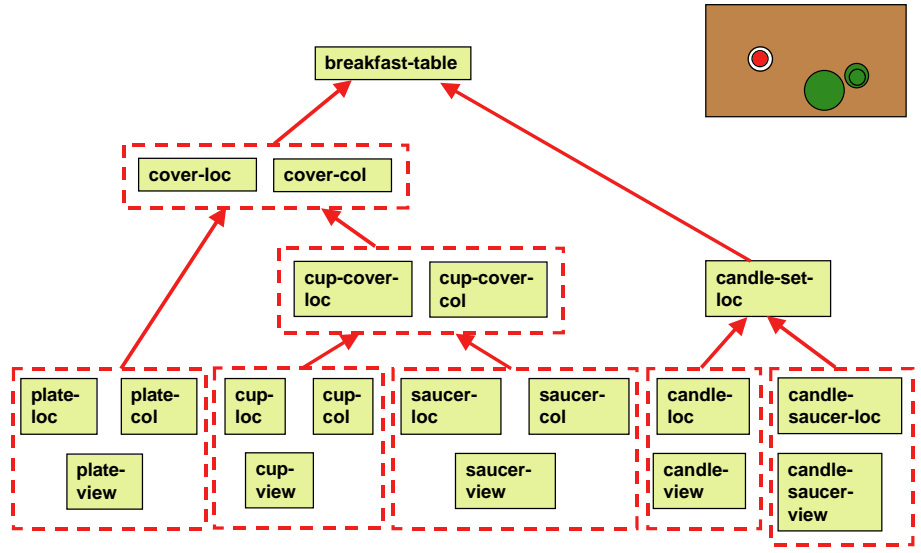
Basic design criteria:

- Ignore weak correlations (poor predictive power)
- Cluster strongly correlated random variables into aggregates
- Provide representative aggregate descriptions



Example: Joint probability table size of $|D|^7$ is changed to $|D|^4 + |D|^5$ ($|D|$ = domain size).

Example: Dinner Table



Representative Aggregate Properties

Shorthand:

$$P(\underline{A}_1, \underline{A}_2, \dots, \underline{A}_M) = P(\overbrace{A_{11}A_{12} \dots A_{1N_1}}^{\text{object 1}}, \overbrace{A_{21}A_{22} \dots A_{2N_2}}^{\text{object 2}}, \dots, A_{M1}A_{M2} \dots A_{MN_M})$$

Assume that objects \underline{A}_1 to \underline{A}_K are clustered into an aggregate \underline{B}_1 with properties $B_{1n} = f_n(\underline{A}_1, \dots, \underline{A}_K)$, $n = 1 \dots N$. The B_{1n} are **representative** aggregate properties of $\underline{A}_1 \dots \underline{A}_K$ with respect to $\underline{A}_{K+1} \dots \underline{A}_M$ if

$$P(\underline{A}_{K+1} \dots \underline{A}_M \mid \underline{A}_1, \dots, \underline{A}_K) \approx P(\underline{A}_{K+1} \dots \underline{A}_M \mid \underline{B}_1)$$

We assume that all properties of an aggregate are representative of its parts w.r.t. the rest of the world.

Partonomy Probability Assignments

Given a basic JPD $P(\underline{A}_1, \underline{A}_2, \dots, \underline{A}_M)$, then the JPDs of all aggregates \underline{B}_i are determined by the functional mappings $\underline{B}_{in} = f_n(\underline{A}_1, \dots, \underline{A}_K)$.

$$P(\underline{B}_{in}) = \sum_{\mathbf{a}_{in} = f_n(\mathbf{a}_1, \dots, \mathbf{a}_k)} P(\underline{A}_1, \dots, \underline{A}_K)$$

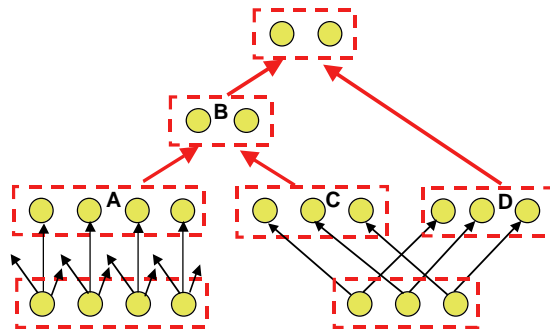
Similarly:

$$P(\underline{B}) = P(\underline{B}_{i1} \dots \underline{B}_{iN}) = \sum P(\underline{A}_1, \dots, \underline{A}_K)$$

$$\begin{aligned} \mathbf{b}_{i1} &= f_1(\mathbf{a}_1, \dots, \mathbf{a}_k) \\ \wedge \mathbf{b}_{i2} &= f_2(\mathbf{a}_1, \dots, \mathbf{a}_k) \\ &\dots \\ \wedge \mathbf{b}_{iN} &= f_N(\mathbf{a}_1, \dots, \mathbf{a}_k) \end{aligned}$$

Probabilistic Inferences

Context information:
 $P(\underline{B}) \Rightarrow P'(\underline{B})$
 - propagate up
 - propagate horizontally
 - propagate down



Unambiguous image evidence:

- $P(\underline{A}) \Rightarrow P'(\underline{A})$ by naive Bayes estimation
- propagate up

Ambiguous image evidence:

- network copies for each alternative
- $P(\underline{C}) \Rightarrow P'(\underline{C})$ by naive Bayes estimation
- propagate up

Yes/no Context Information

"Aggregate B is present"

Assume binary mapping $f(\underline{b}) = \begin{cases} 1 & \text{if } \underline{b} \text{ satisfies aggregate properties} \\ 0 & \text{otherwise} \end{cases}$

Consistency constraint: $\sum P'(\underline{B}) = \sum P(\underline{B}) = 1$

All $P(\underline{B})$ with $f(\underline{b}) = 1$ are upscaled by constant factor $1 / \sum_{f(\underline{b})=1} P(\underline{B})$

$$P'(\underline{B}) = P(\underline{B}) / \sum_{f(\underline{b})=1} P(\underline{B})$$

Propagating Down

$P(\underline{B}) \Rightarrow P'(\underline{B})$ with $B_{1n} = f_n(\underline{A}_1, \dots, \underline{A}_K)$, $n = 1 \dots N$

How does the change of $P(\underline{B})$ affect $P(\underline{A}_1, \dots, \underline{A}_K)$?

Shorthand: $\underline{A} = \underline{A}_1, \dots, \underline{A}_K$ $\underline{B} = f(\underline{A})$

$P'(\underline{B}) = s(\underline{B}) P(\underline{B})$

$$P'(\underline{A}) = s(\underline{B}) P(\underline{A}) \quad \text{for all } \underline{b} = f(\underline{a})$$

Propagating Horizontally

Assume that $\underline{A}_1 \dots \underline{A}_N$ are parts of an aggregate \underline{B} .

Assume that $P(\underline{A}_1) \Rightarrow P'(\underline{A}_1)$

How does the change of $P(\underline{A}_1)$ affect $P(\underline{A}_1 \dots \underline{A}_N)$?

$$P'(\underline{A}_1) = s(\underline{A}_1) P(\underline{A}_1)$$

$$\begin{aligned} P'(\underline{A}_1 \dots \underline{A}_N) &= s(\underline{A}_1) P(\underline{A}_1) P'(\underline{A}_2 \dots \underline{A}_N | \underline{A}_1) \\ &= s(\underline{A}_1) P(\underline{A}_1) P(\underline{A}_2 \dots \underline{A}_N | \underline{A}_1) \\ &= s(\underline{A}_1) P(\underline{A}_1 \dots \underline{A}_N) \end{aligned}$$

For Bayes Net representation:

$$P'(\underline{A}_1 | \underline{A}_i \dots \underline{A}_k) = s(\underline{A}_1) P(\underline{A}_1 | \underline{A}_i \dots \underline{A}_k)$$

$$P'(\underline{A}_n | \underline{A}_i \dots \underline{A}_k) = P(\underline{A}_n | \underline{A}_i \dots \underline{A}_k) \quad n \neq 1$$

Propagating Up

Assume that $\underline{A}_1 \dots \underline{A}_K$ are parts of an aggregate \underline{B} .

Assume that $P(\underline{A}_1) \Rightarrow P'(\underline{A}_1)$

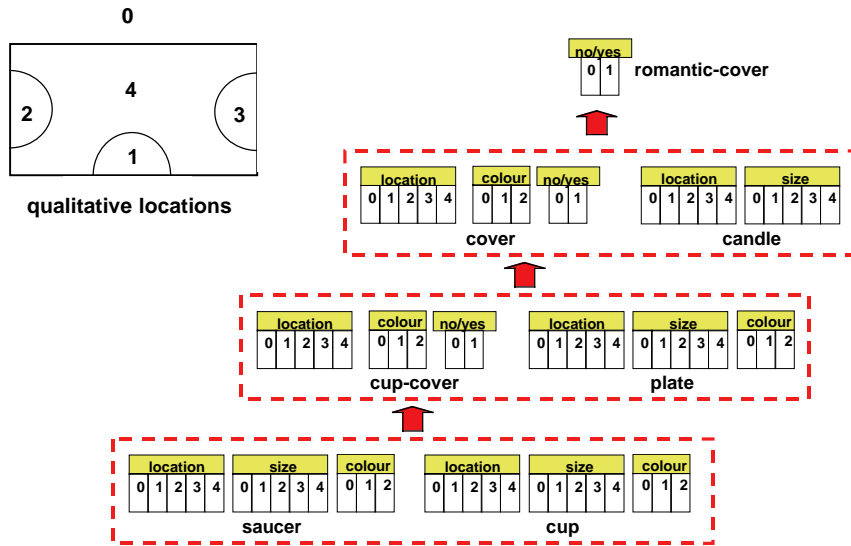
How does the change of $P(\underline{A}_1)$ affect $P(\underline{B})$?

From horizontal propagation we get

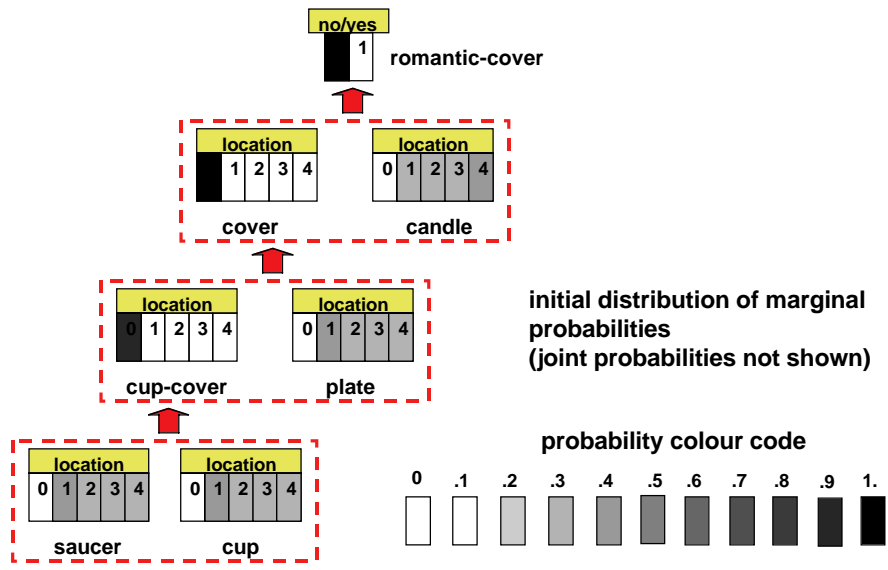
$$P'(\underline{A}_1 \dots \underline{A}_K) = s(\underline{A}_1) P(\underline{A}_1 \dots \underline{A}_K)$$

$$\begin{aligned} P'(\underline{B}) &= \sum P'(\underline{A}_1 \dots \underline{A}_K) \\ &= b_1 = f_1(a_1, \dots, a_k) \\ &\wedge b_2 = f_2(a_1, \dots, a_k) \\ &\dots \\ &\wedge b_N = f_N(a_1, \dots, a_k) \end{aligned}$$

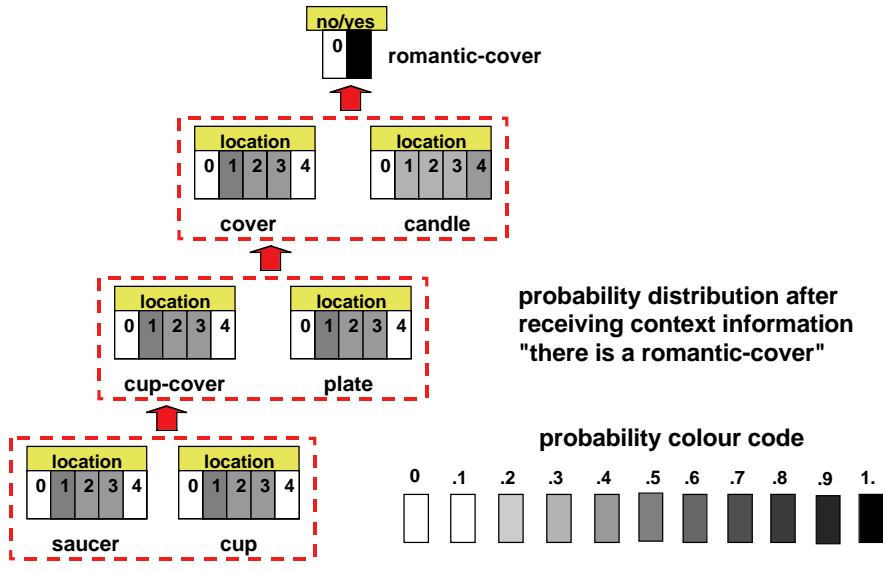
Simulation Experiment



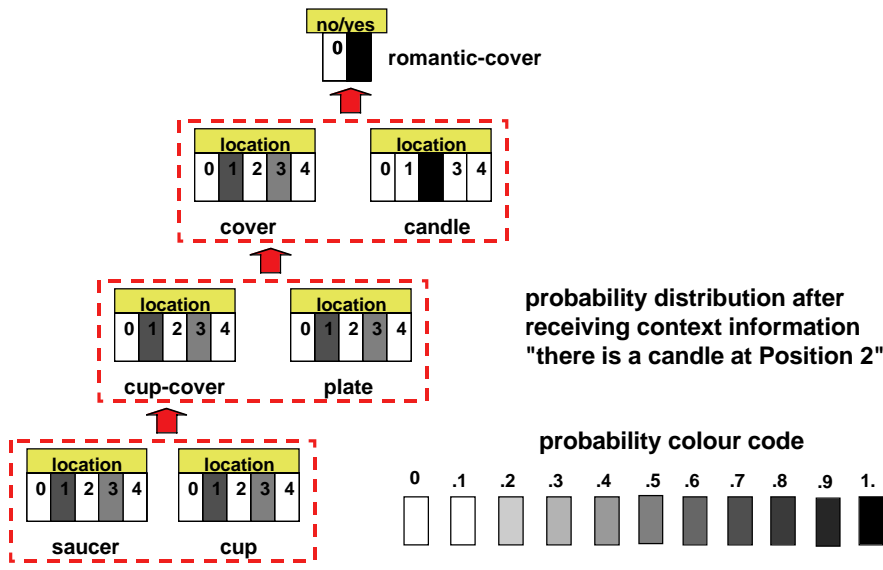
Location Probabilities of Partonomy Items (1)



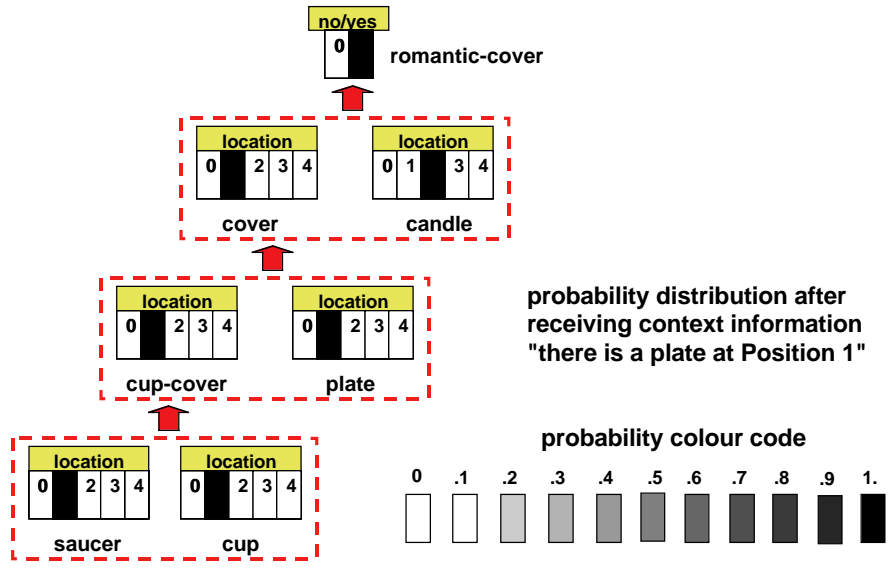
Location Probabilities of Partonomy Items (2)



Location Probabilities of Partonomy Items (3)



Location Probabilities of Partonomy Items (4)



Conclusions

- Belief revision in partonomies can be achieved by local propagation
- Expected feature values can be made available at any time during the interpretation process
 - => educated guesses
 - => best-first search
 - => top-down control of image analysis
- "Weak" integration with logic-based interpretation

Further Work

- **Extend probabilistic reasoning to include taxonomical structures**
- **Develop preference measure for interpretation steps**
- **Develop resource-limited belief propagation**
- **System integration**